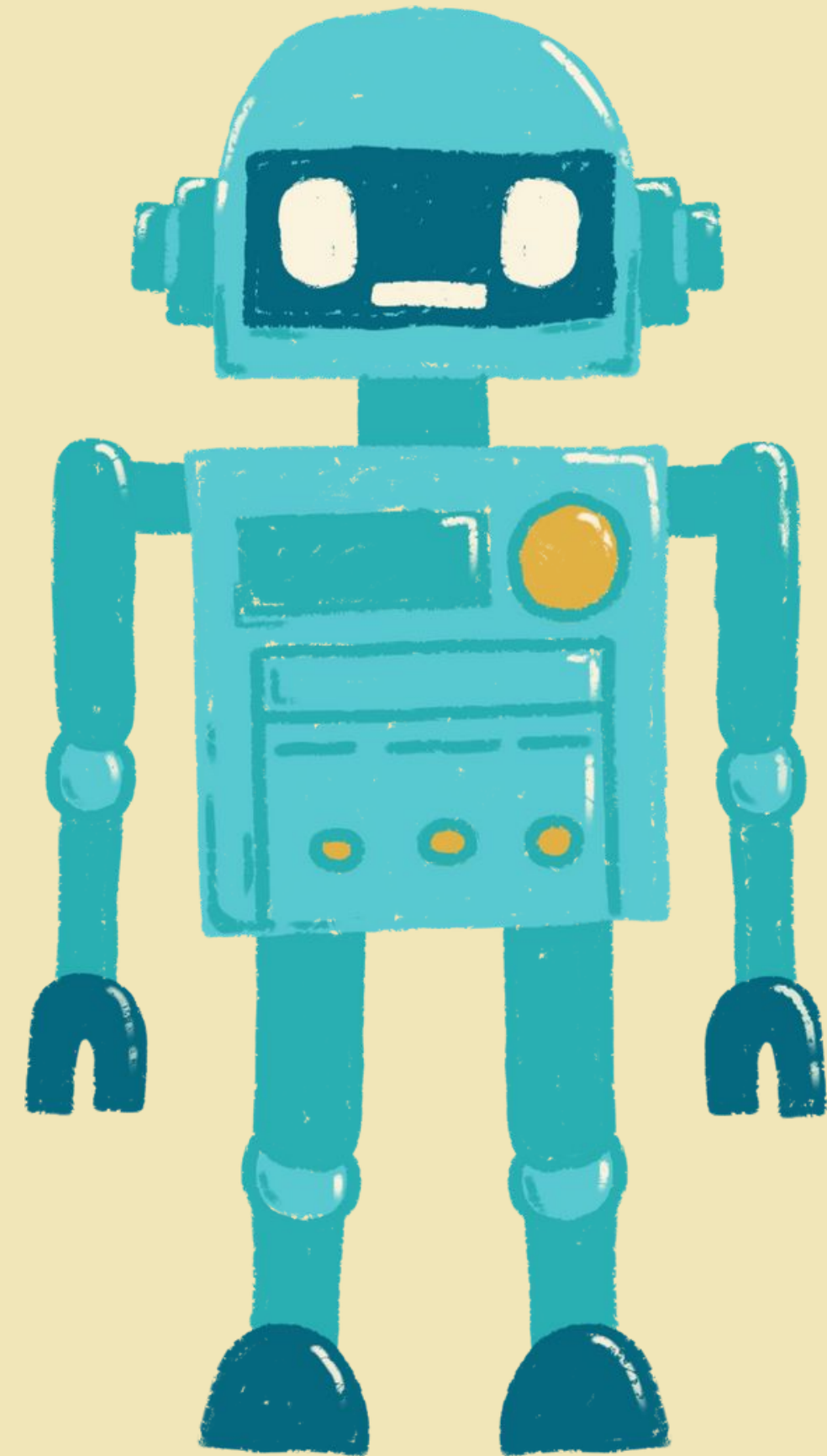


Gesture Guide

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Team Members

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Coord: Maryam Al-Safran

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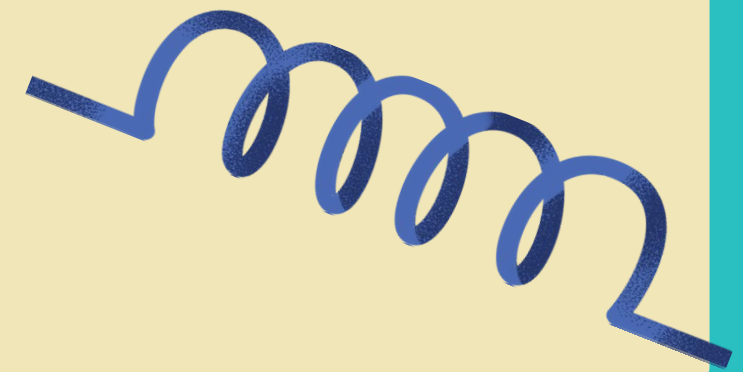
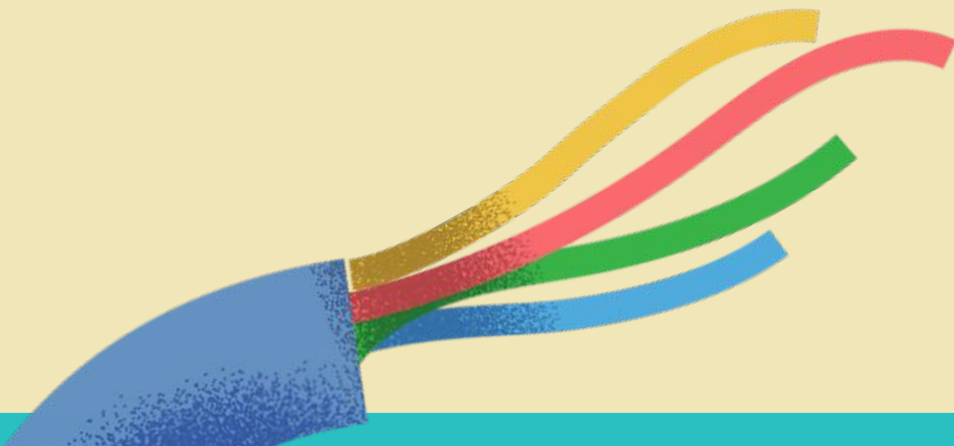
REC: Maha Al-Dehemi



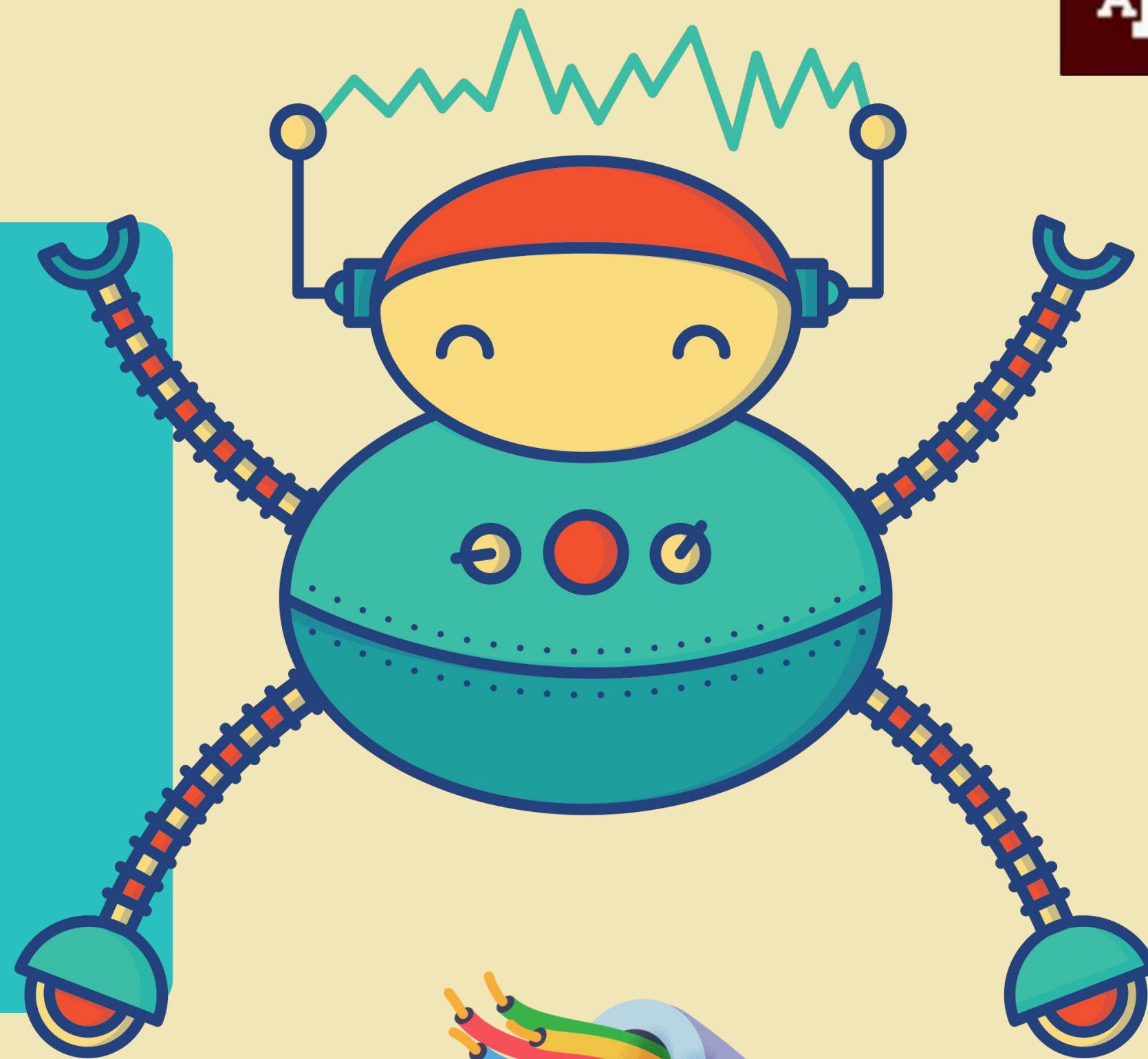


Table Of Contents

1 Introduction	2 Problem Statement	3 Proposed Solution	4 Functional Modeling	5 Block Diagram	6 Relays Prototype Design
7 Servo Motor Prototype Design	8 Technical Standards and constraints	9 Risks	10 Performance Criteria	11 Advantages of our Project	12 Simulation Results
13 Analysis for designed circuits and program code	14 Mechanical Structure	15 Experimental Testing and Results	16 Functional Modeling	17 Troubleshooting	18 Conclusion
		19 Website	20 Reference		



1. Introduction





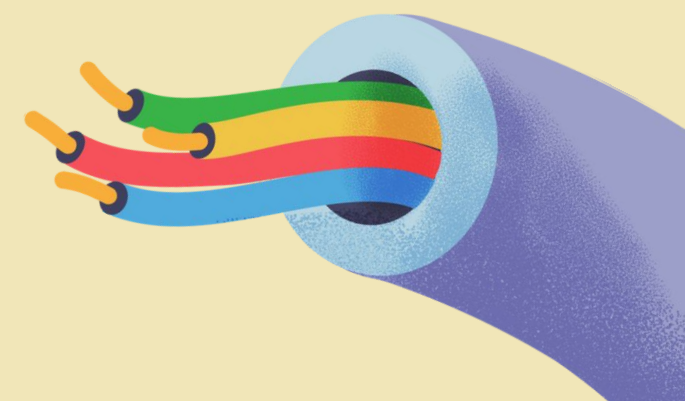
Introduction

- Physical impairments may make it more difficult for a person to interact with others and their environment.

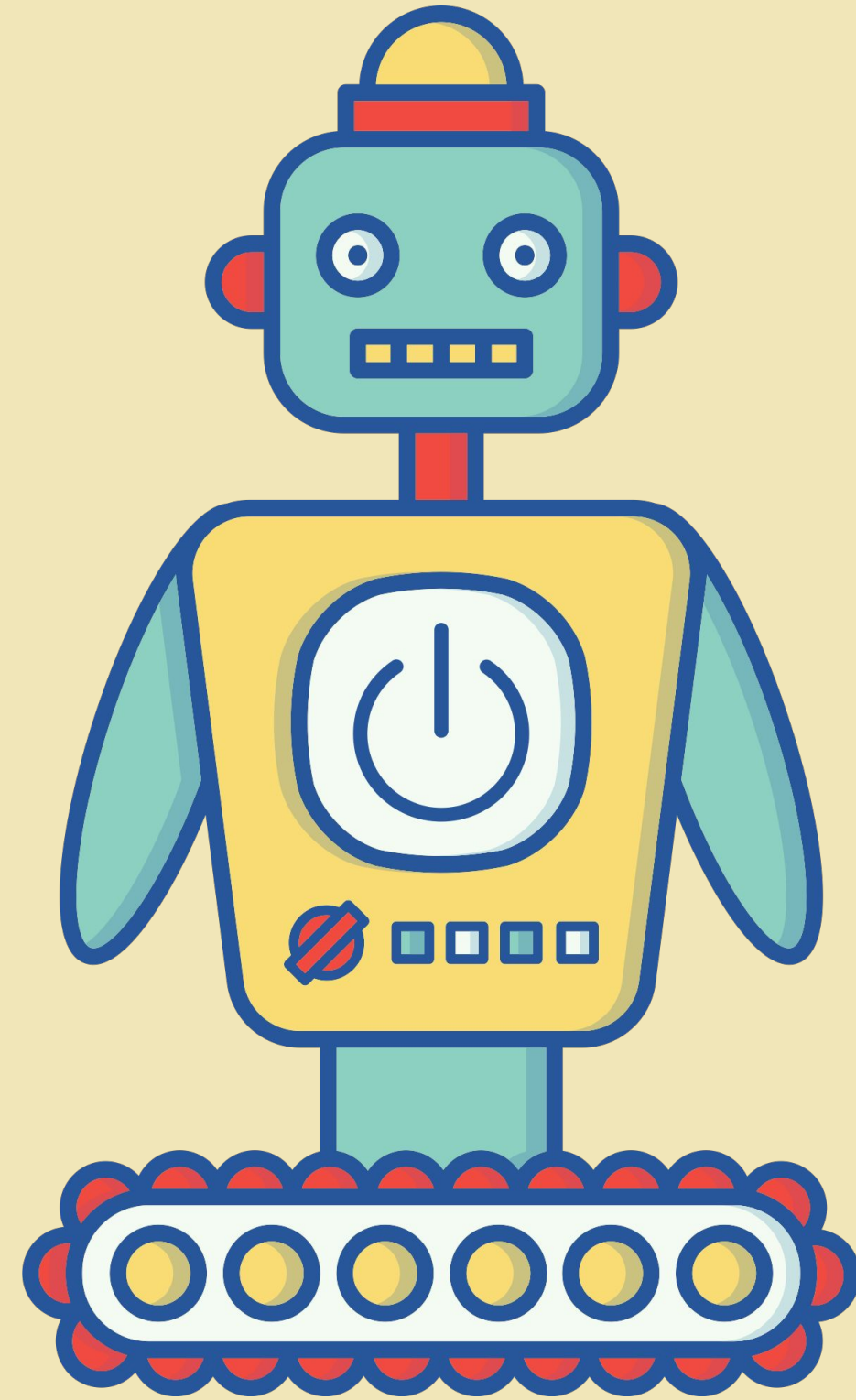
- Technological developments have created new opportunities for people with physical disabilities to enhance their lives.

- Guide gesture control is one of the technologies that enables a person with a disability to use finger movements to interact with devices

- The use of hand gesture control could enable people with physical disabilities to carry out tasks that might not be possible.



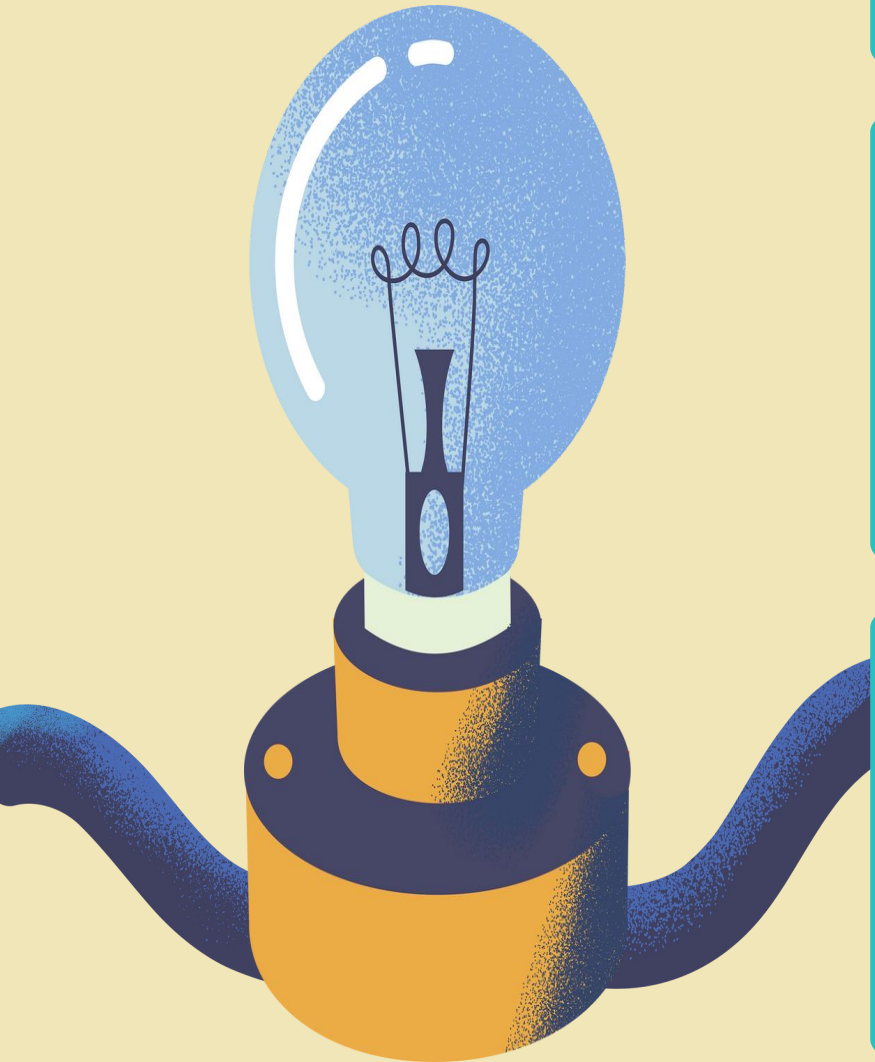
2. Problem Statement

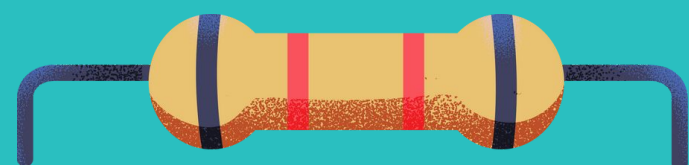




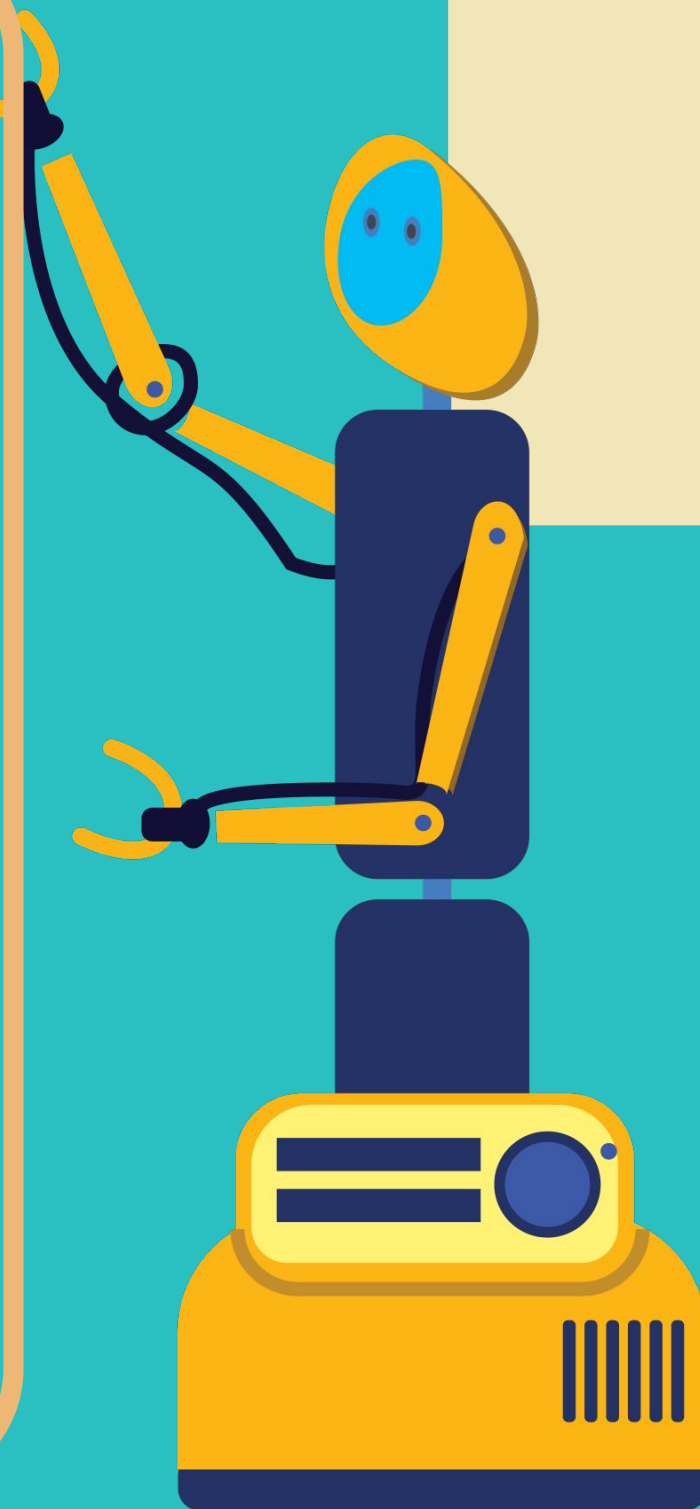
Problem Statement

- Individuals with physical disabilities face significant challenges in maintaining independence within their homes.
- Current assistive technologies are costly and have limitations.
- There is a need for a cost-effective and nonintrusive solution to enhance the quality of life for patients with spinal cord injuries (SCI).





3. Proposed Solution



Proposed Solution

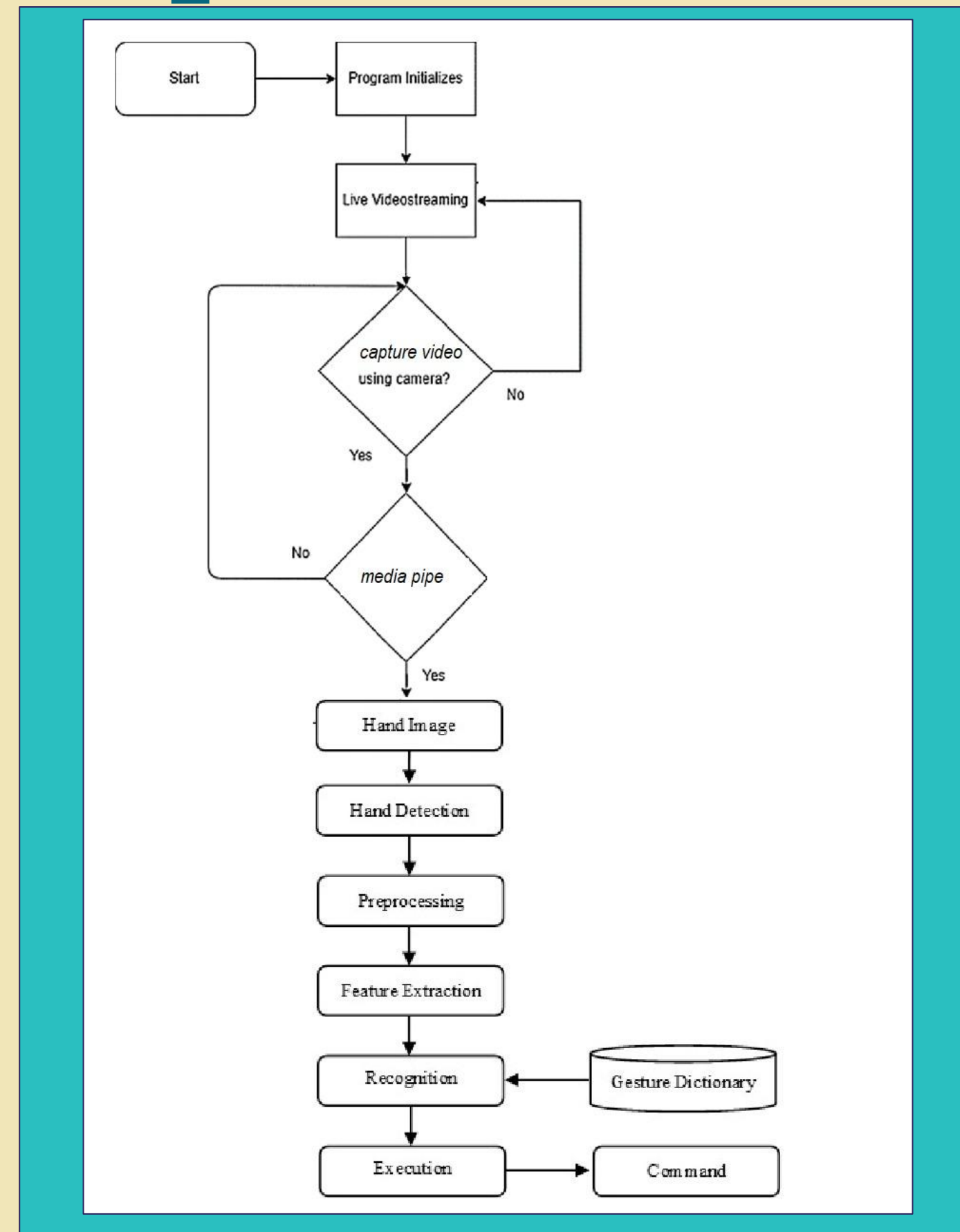


Figure 1: Proposed solution

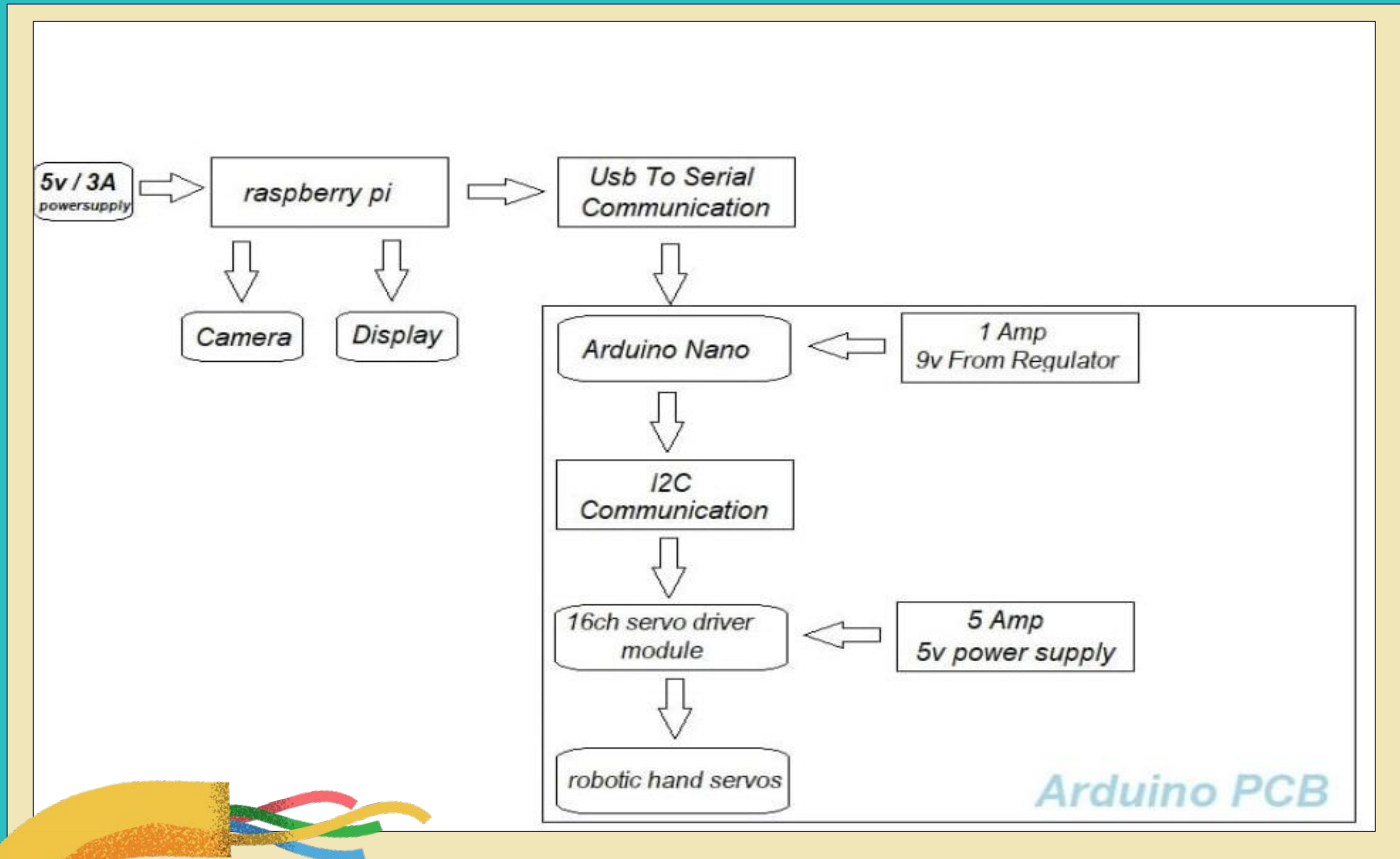


Figure 2: System Block Diagram

4. Functional Modeling

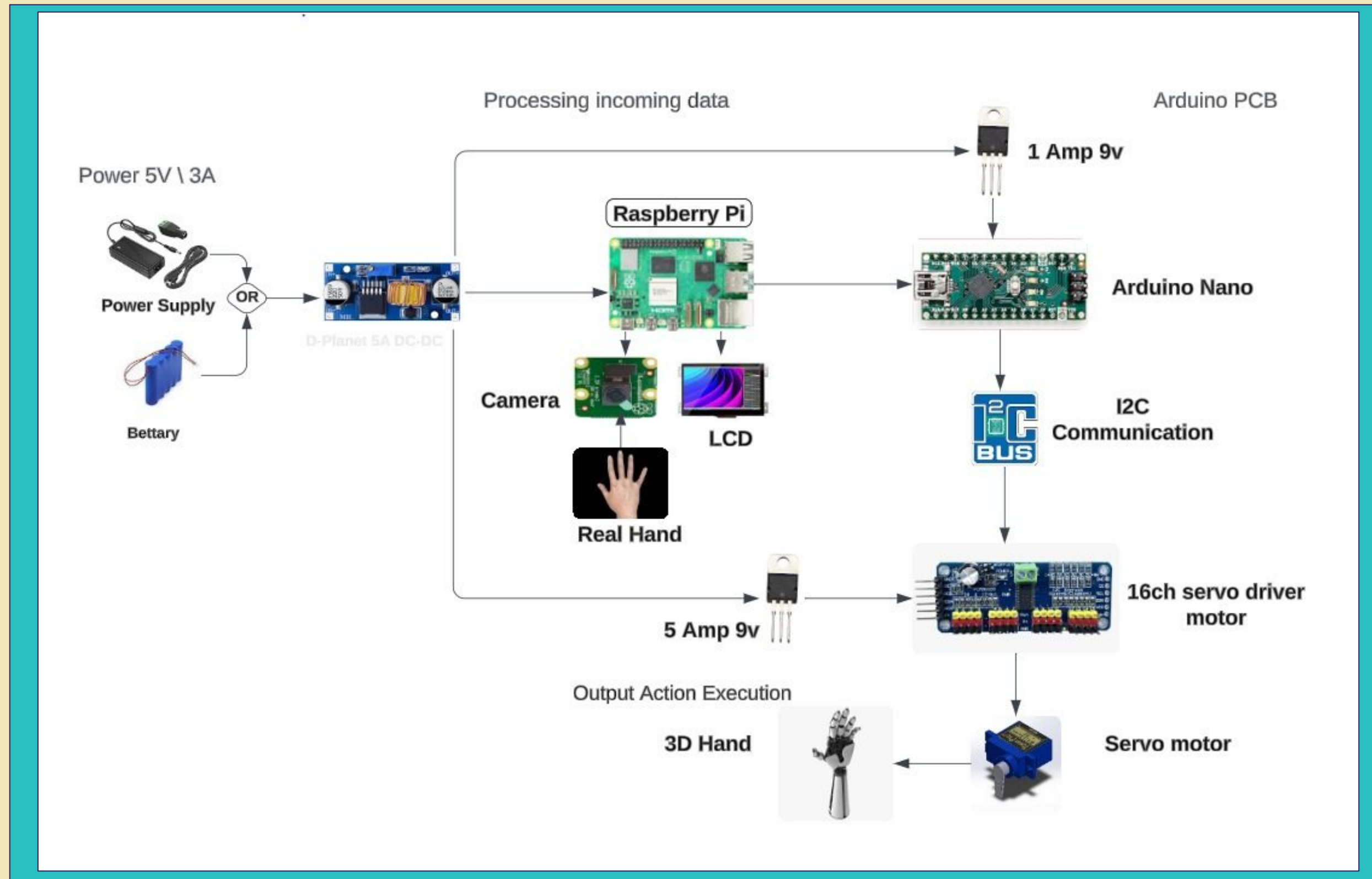


Figure 3 : Functional Modeling (using Components diagram)

5. Block Diagram



Figure 4: Block diagram

6. Relays Prototype Design

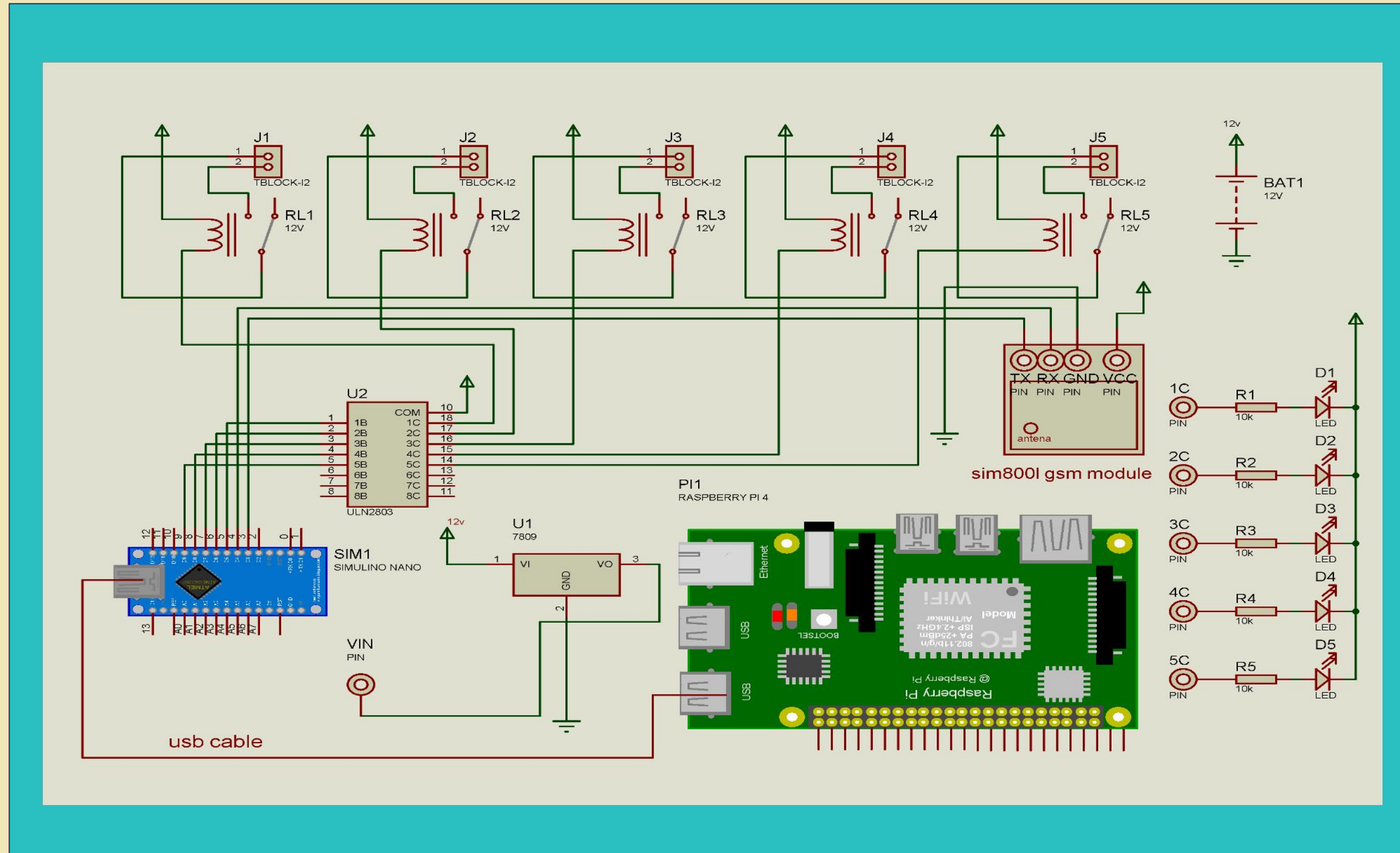


Figure 5 :Prototype 1 Design

7. Servo Motors Prototype Design

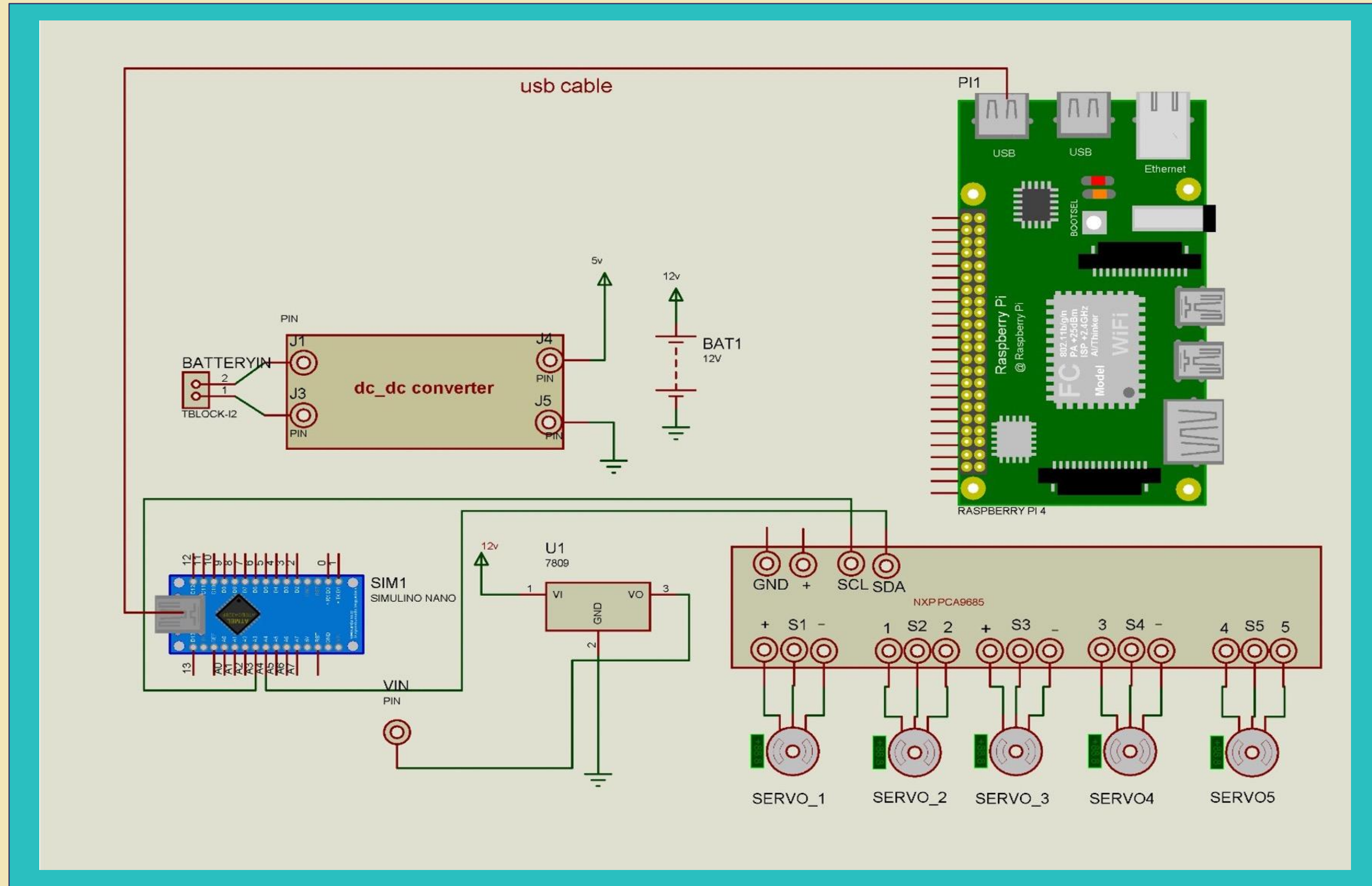
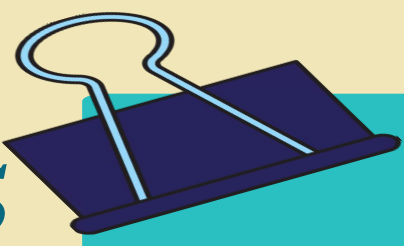


Figure 6 :Prototype 2 Design



8. Technical Standards and Constraints



- IEEE 11073

STANDARDS

Gesture recognition
Accuracy

Operation Range

CONSTRAINTS

Software Compatibility

Cost Constraints



9. Risks:

Technical

- Gesture Recognition Failures.
- Hardware Malfunctions.
- Latency Issues.

Operational Risks:

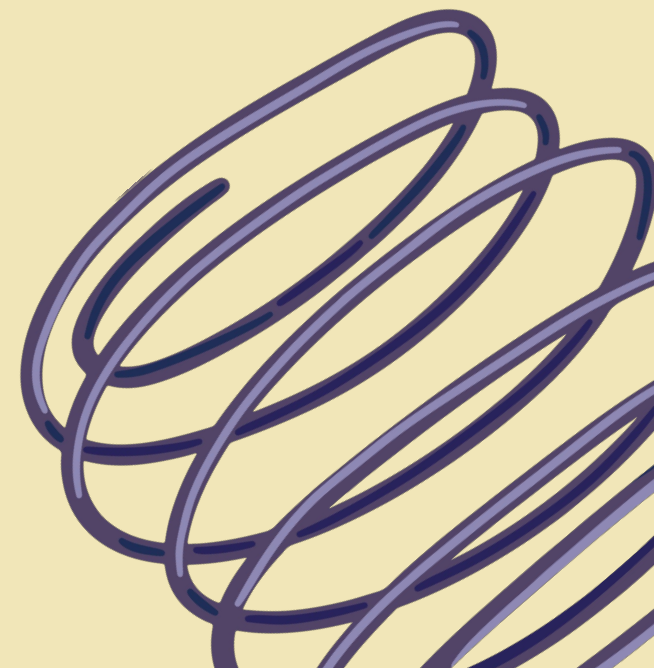
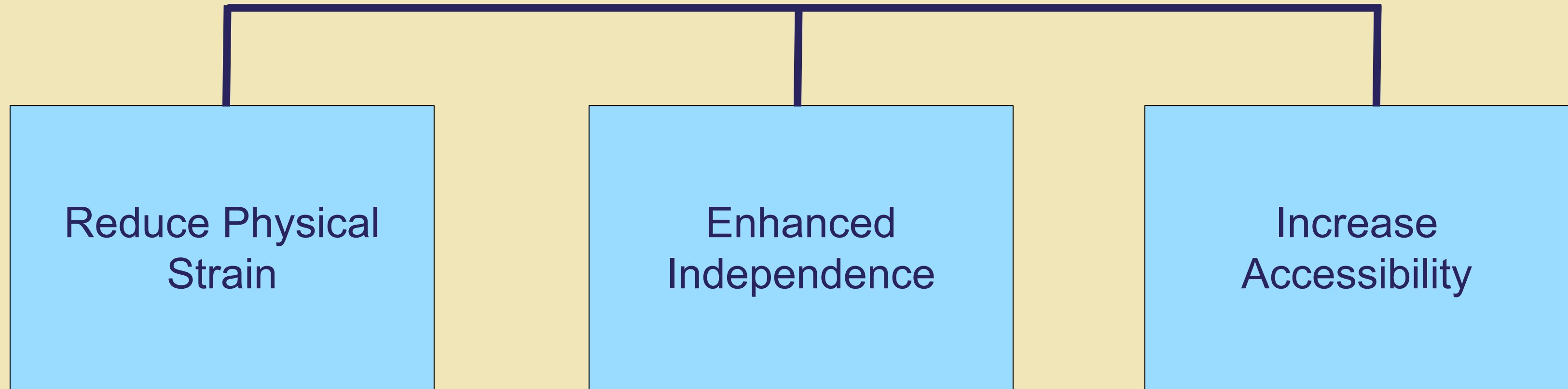
- Integration Issues.

10. Performance Criteria

		Criteria			
		Environmental	Economical	Performance	Attainability
Existing Solutions	Our Project	Fewer procedural operations after training and testing, Lower power consumption and excellent user assistant.	Easy to use, technically inexpensive and content based project.	High Performance more than MFDT and HMM	High
	MFDT	Low impact	Moderate Considerations	Moderate performance	High
	HMM	Fewer uses than MFDT, lower power.	It needs training from the user first and then dealing with it	Similar performance of MFDT	Moderate
	3D-BHG	Low impact	High Considerations	High performance	Moderate
	CGA	Low impact	High Considerations	High performance	Moderate

Table 1 : Performance Criteria

11. Advantages of our Project





12. Simulation Results

Recognition Rates

- Percentage of accurately recognized gesture across different users
($\geq 90\%$ accuracy)

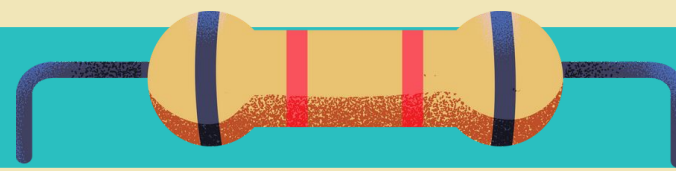
Latency Measurements

Average response time for
gesture detection to
system action
(< 100 ms)

Task Completion Time

Average time taken to
complete specific task
using our device vs.
traditional method
(< 1 sec)

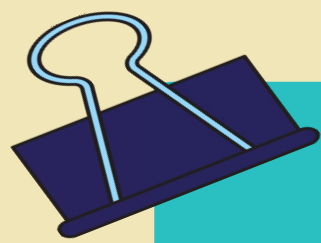




13. Analysis for designed circuits and program code

- Component Verification
- Connection Integrity
- Signal Timing
- Output Behavior





14. Mechanical Structure



Prototype House

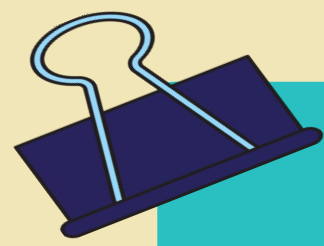


Figure 7 : Prototype House

3D - Hand



Figure 8 : 3D Hand



Gesture Recognition Accuracy

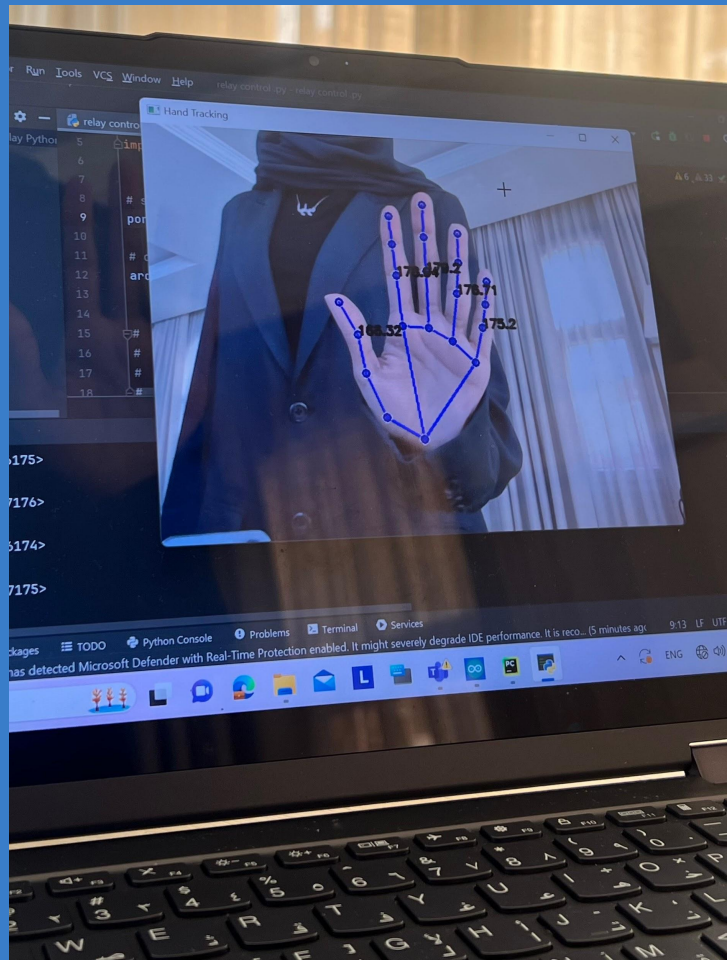


Figure 9 : Gesture Recognition Accuracy

Gesture Recognition With Outside Noise

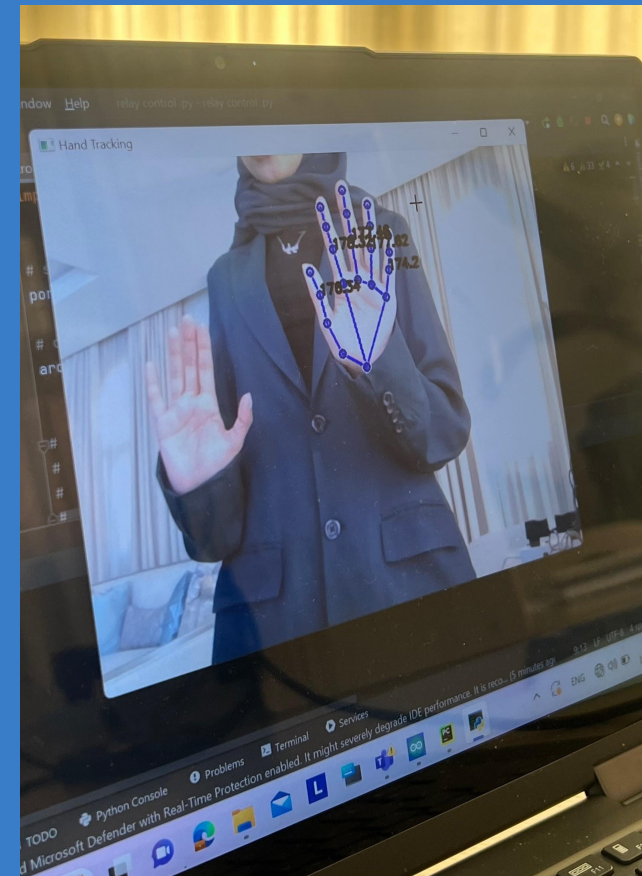


Figure 10 : Gesture Recognition With outside Noise

Gesture Recognition Under Different Conditions Ex: Dim lights

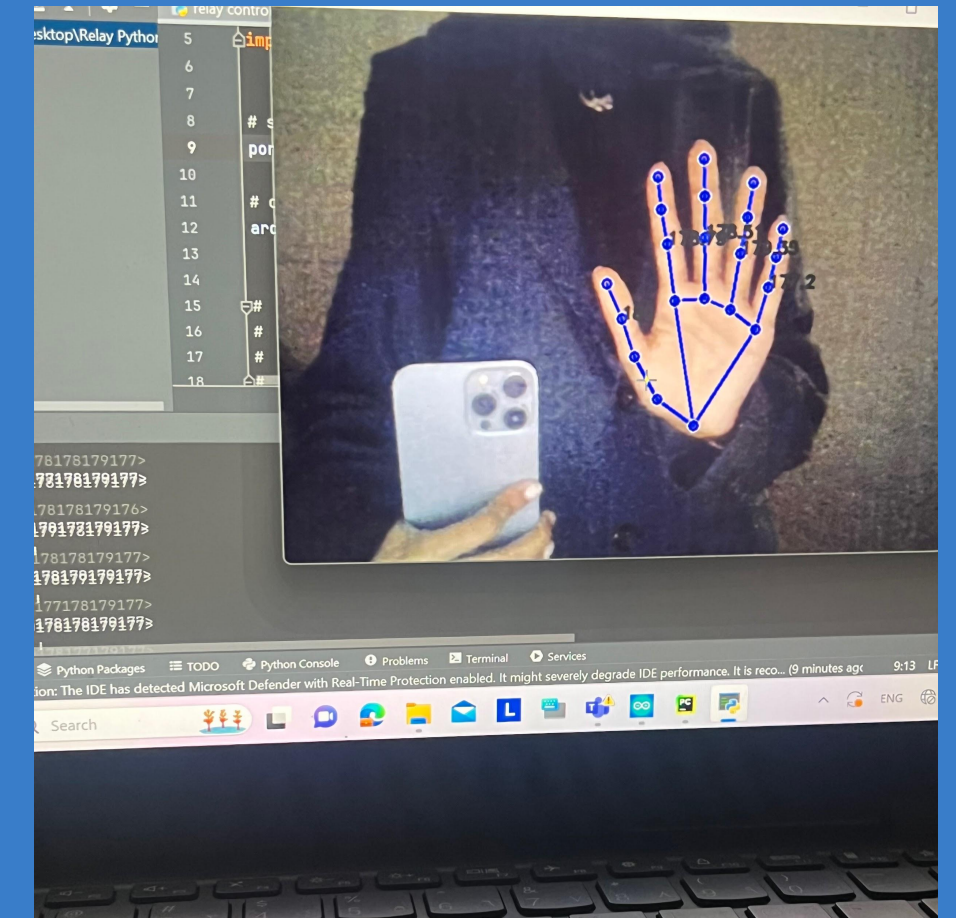
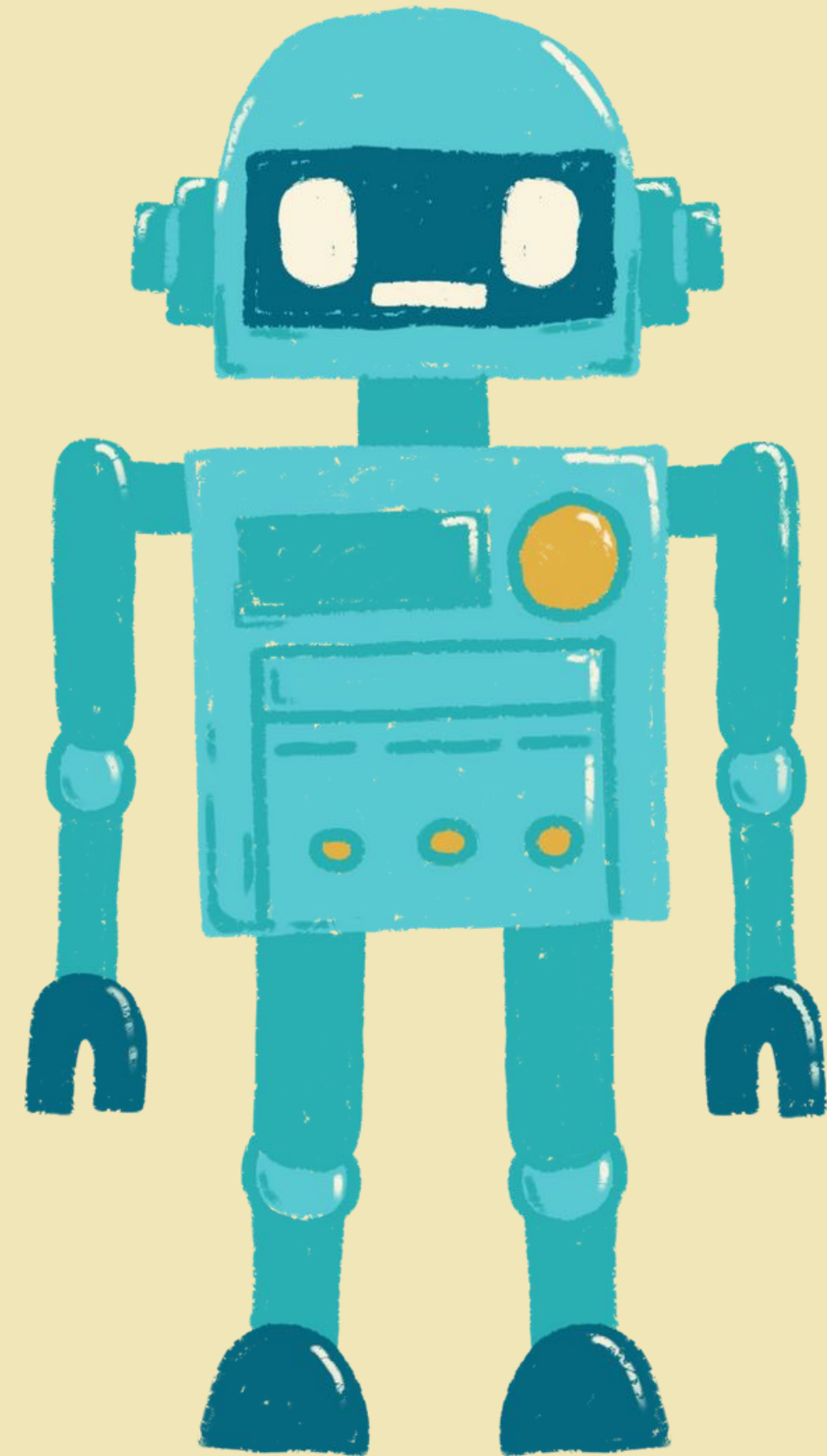


Figure 11 : Gesture Recognition Under Different Conditions

16. Functional Prototyping

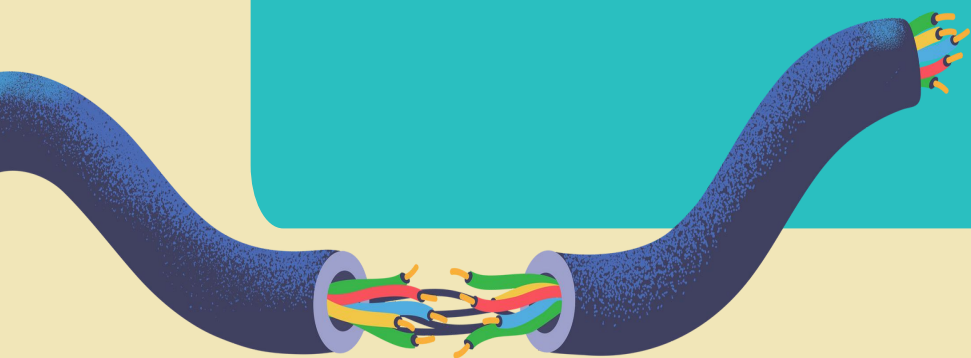




17. Troubleshooting

Hardware

- Check power to components.
- Verify wiring and connections.
- Ensure microcontroller is functioning.



Software

- Review code for errors.
- Check gesture interpretations.
- Verify timing functions.



18. Conclusion



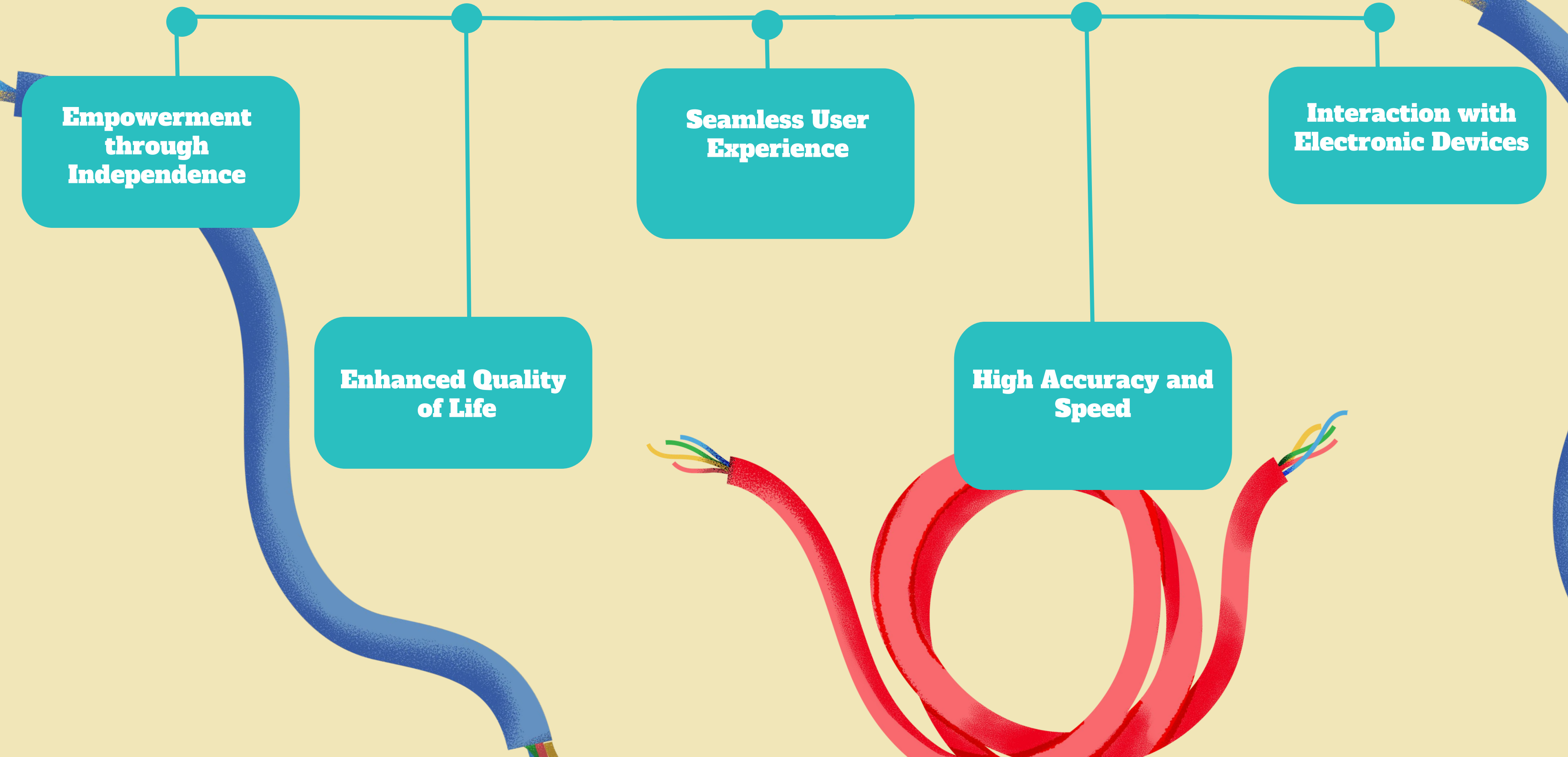
**Empowerment
through
Independence**

**Enhanced Quality
of Life**

**Seamless User
Experience**

**High Accuracy and
Speed**

**Interaction with
Electronic Devices**



19. Future Recommendation & Improvement



**Continuous User
Feedback**

**Customization
Options**

**Integration with
Other Technologies**

Target New Market

**Partnership With
Organizations**

20. Website

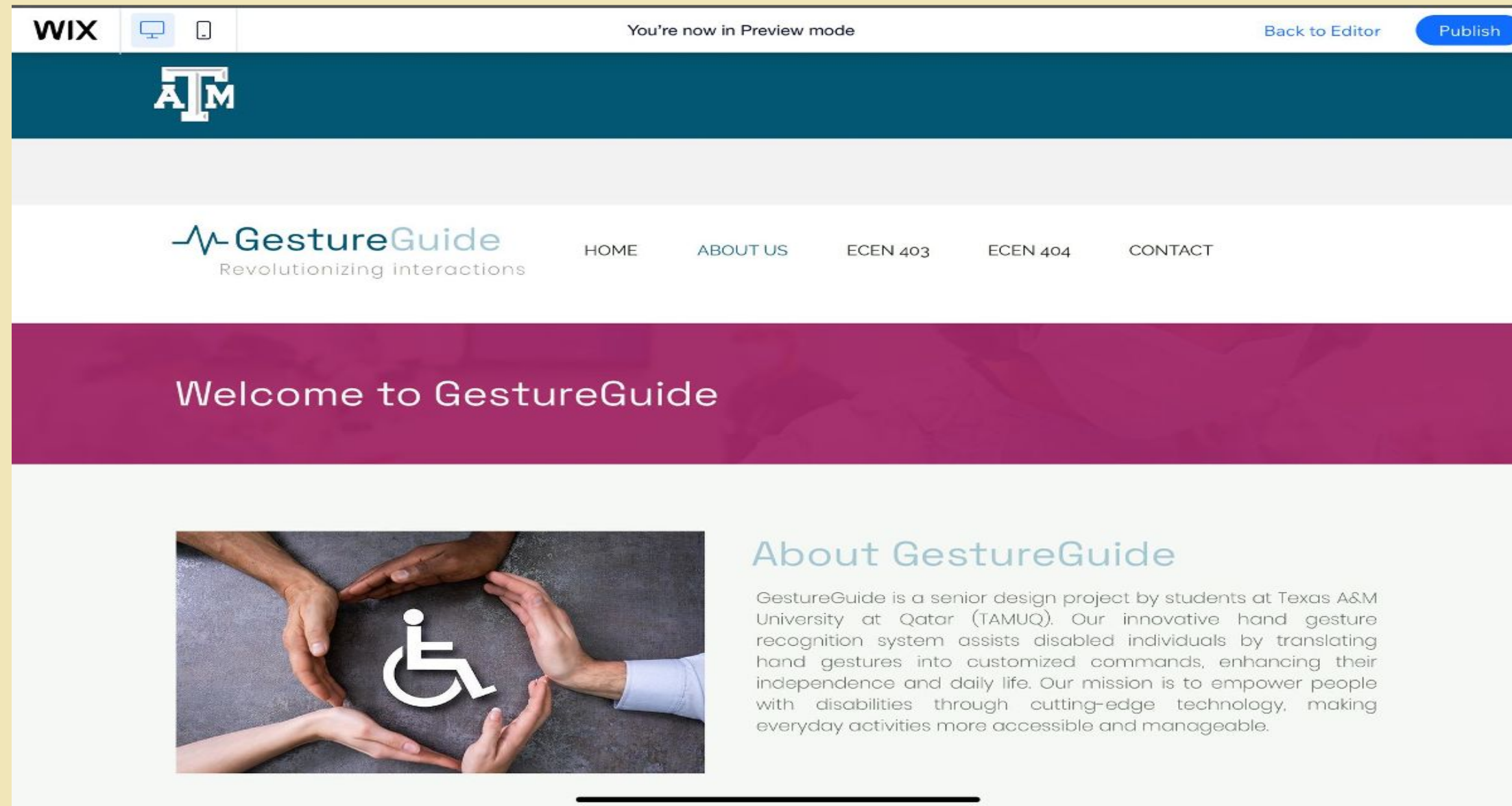


Figure 12 : Website

<https://gestureguides.com>



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- Wenjin Zhang, Jiacun Wang, and Fangping Lan (2021)
- Short-Term Sampling Neural Networks
- IEEE/CAA J. Autom. Sinica, vol. 8, no. 1, pp. 110-120

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- Stella Nadar, Simran Nazareth, Kevin Paulson, Nilambari Narkar (2021)
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Thank you !

Any Questions?

